







CITYNEXUS

A Digital Twin Application Linking Mobility and Air Quality for Sustainability Transition

The Challenge: transforming Amager Vest







- The City of Copenhagen and the Local Council of Amager Vest (LCAV) aim to reduce traffic congestion and promote urban quality of life.
- A key proposal involves transforming high-speed roads in Ørestad (Amager Vest), a diverse area near the city center with about 25,000 residents, to reduce traffic, improve air quality, and enhance living spaces.
- Inspire other districts and municipalities to match mobility and economic needs with climate action and environmental health.





CITYNEXUS: Aims and Scope





- Destine Digital Twin Use-case for sustainable urban interventions;
- Interactive system for generating policy-relevant
 user-defined 'what-if' scenario simulations
- Possibility to assess the impact of decisions relating to traffic, infrastructure, land use and population on mobility and air quality
- Collaborative platform to experiment strategies and test solutions to facilitate evidence-based decision-making at municipality level





'What if' scenario capabilities







- Road tunnelling: simulate the tunnelling of any existing road segment
- Change Points of Interest (POIs) and Population: adding new POIs and increasing population.
- **E-vehicle and active mobility:** customize the proportion of e-vehicles, bicycles and pedestrians.
- Low Emission Zones (LEZ) Creation: identify roads where motorized circulation is prohibited to vehicles.
- Adjusting Speed Limits: change speed limits of specific road segments.
- Traffic Fleet Composition: Alter the proportion different vehicle types (electric vehicles, bicycles, cars)





Scenario simulation parameters





Pollutants selection

Up to 5 different pollutants (CO2, CO, HC, NO2, PMx)



Time-window selection

Up to 8 selectable time-windows, each representing a 3-hour block



Day-type selection

Option to choose between a weekday or weekend.



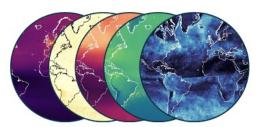


Key input datasets

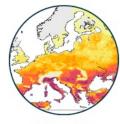




High Frequency Location Based mobility data



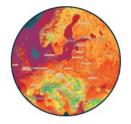
Sentinel-5P TROPOMI L2 (NO2, SO2, CO, O3 and clouds)



ECMWF ERA5 hourly estimates



CORINE Land Cover at 100m resolution



Global Wind Atlas



Google Environmental Insight Explorer



EEA Airbase ground monitoring stations



OpenStreetMap





Input Data from DestinE Data Portfolio





- Sentinel-5P TROPOMI Level2 daily tropospheric NO2, SO2, CO, O3 vertical column densities;
- Copernicus Digital Elevation Model of Europe at 10m resolution;
- ECMWF ERA5 hourly estimates for different meteorological variables;
- CORINE Land Cover from the Copernicus Land Monitoring Service at 100m.





HFLB Mobility data



CityNexus relies on **High-Frequency Location Based (HFLB)** mobility data, that is data
precisely tracking the location of GPS-enabled logging devices over time.

This is used to provide **key insights** into commuting patterns, traffic flows, congestion rates and overall mobility dynamics



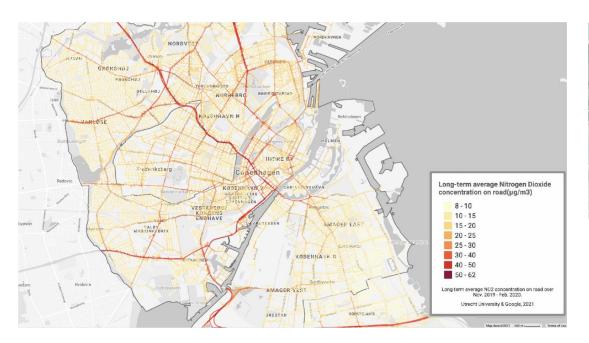




GEIE - Air Quality Labs data



Data gathered from mobile mapping campaigns (Google Environmental Insight Explorer - Air Quality Labs data).





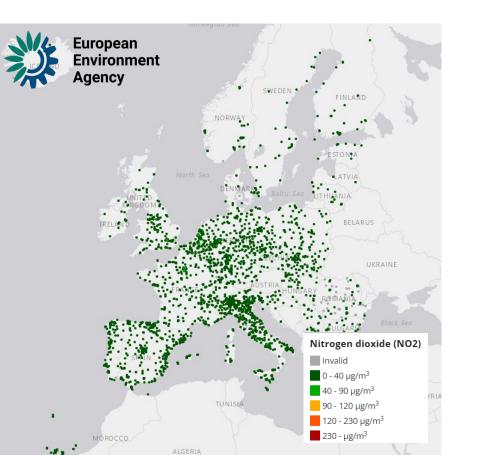
Environmental Insights Explorer





EEA AirBase Air Quality data





- AirBase multi-annual time series of air quality measurement data different air pollutants (NO2)
- To overcome the limited number of air quality stations in **Denmark** (12-15 stations), **Germany** (>300 stations) and **Poland** (120-150 stations) were also included.





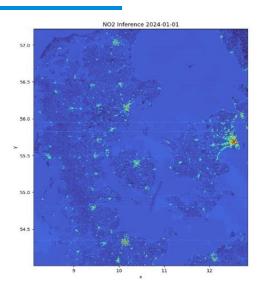
CityNexus Models





Local Mobility & Pollutant Concentration Model

To account for pollutants primarily generated by vehicular traffic



Regional Air Quality Model

To account for pollutants generated as result of all human activities





Local Mobility & Pollutant Concentration Model



Mobility Data Cleaning and Filtering

Street Network & Spatial Features

Origin-Destination Matrix

Detection of Transport Modes

Deep Gravity Model

Traffic & Emissions Simulation

Pollutant Concentration Model

Remove low-accuracy entries and identifying "stops"

Pre-process OSM network, link H3 cells with land use and POI data

Map O/D pairs into H3 cells, compute in/out flows.

Identify trips by pedestrian, cyclist, vehicle based on mean speed and standard deviation

Models mobility patterns from O/D matrices and predicts changes under different simulation conditions.

Simulates traffic flows and emission estimates by vehicle type.

A regression model combines Google EIE data with emissions to estimate pollutant concentrations.





Local Mobility & Pollutant Concentration Model: Key steps





Road occupancy

NO2 concentration





Regional Air Quality Model (NO2)



- Gradient boosting methodology to generate 100m-resolution maps of near-surface NO2 concentration;
- Spatial covariates (i.e. DEM, land use data, population density, road density, traffic volume, industrial emissions...) employed as independent variables;
- NO2 measurements from in-situ stations employed as dependent variables.

Training:

using data from air quality stations Germany and Poland to exploit climatic similarities.

Validation

using in-situ air quality measurements and AirBase data from Denmark.

Fine-Tuning

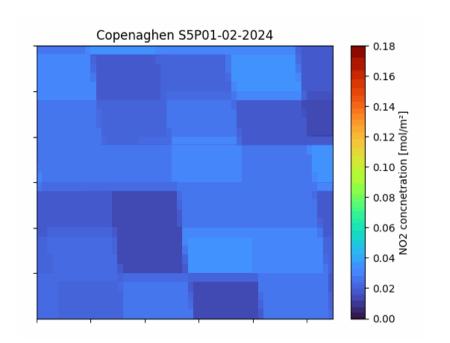
iterative refinement and additional training to improve model accuracy.

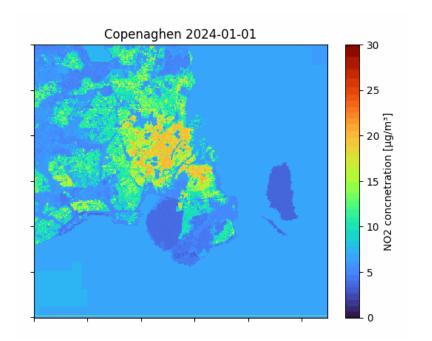




Regional Air Quality Model





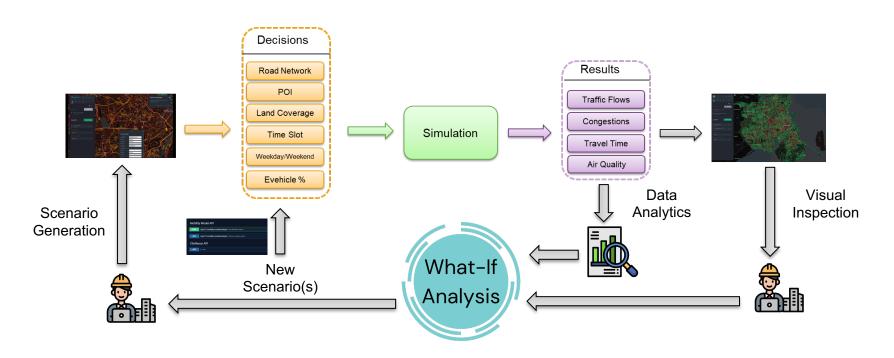






User Workflow









User Interface





- Interactive user interface build on Kepler.gl and OPENAPI
- Visualise a scenario, make modifications, start a simulation and explore results







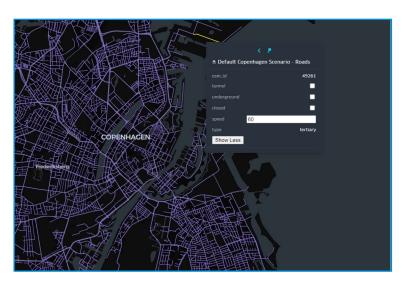


User Interface



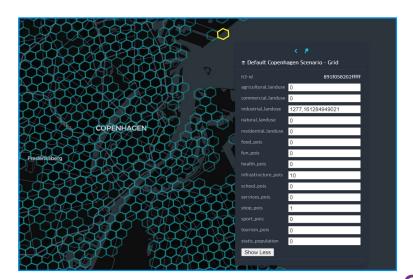
Road Segment Properties

Road Segment Conversion Average Speed Adjustment Road Segment Accessibility



Map Zone Properties

Land use classes change Points of Interest management Population dynamics adjustment







Explainable AI





XAI for *validation and increased trustworthiness* for operational deployment

"validating the system"

mostly on algorithm transparency and global interpretability, to understand how a model was generated and how the system makes predictions.



XAI as support for decision-making and *intelligent assistance*

"improving the system"

global interpretability, to justify the decisional process,

local interpretability, to provide explanations on specific suggestions generated



XAI for *root cause analysis* and explanation

"learning from the system"

global interpretability, to understand how causes/anomalies are found,

local interpretability, to provide explanation on specific findings





Thank You









Local Mobility & Pollutant Concentration Model



SUMO (Simulation of Urban Mobility):

- Open source, highly traffic simulation package developed by the Institute of Transportation Systems at DLR.
- Designed for microscopic and continuous traffic modeling in large networks.
- Supports intermodal simulation, including pedestrians, with a comprehensive toolkit for scenario creation.
- Facilitates detailed analysis of traffic flows, including vehicular and pedestrian traffic in complex urban environments.







Local Mobility & Pollutant Concentration Model



Deep Gravity Model:

- Utilizes deep neural networks to predict mobility flows within a city or region;
- Generates new scenarios based on different parameters;
- Integrates mobility-related variables such as POIs, road infrastructure, population, and land use;
- Able to transfer knowledge to metropolitan areas not previously analysed;
- Offers more accurate predictions than traditional gravity models, especially in areas with scarce data;
- Helps to better understand the motivations behind movements

